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## Introduction & Motivation

**Background:** The rotation of an ellipsoidal particle immersed in a viscous flow is described by the Jeffery orbits equation [1]:  $\dot{\phi}(\dot{\gamma}t) = \frac{1}{2}(\Lambda \cos 2\phi + 1)$ . But, its accuracy is insufficient: it does not always agree with experimental results. We use **platelet simulation** in the blood as a representative example which is related to cardiovascular diseases and COVID-19 [2-3].

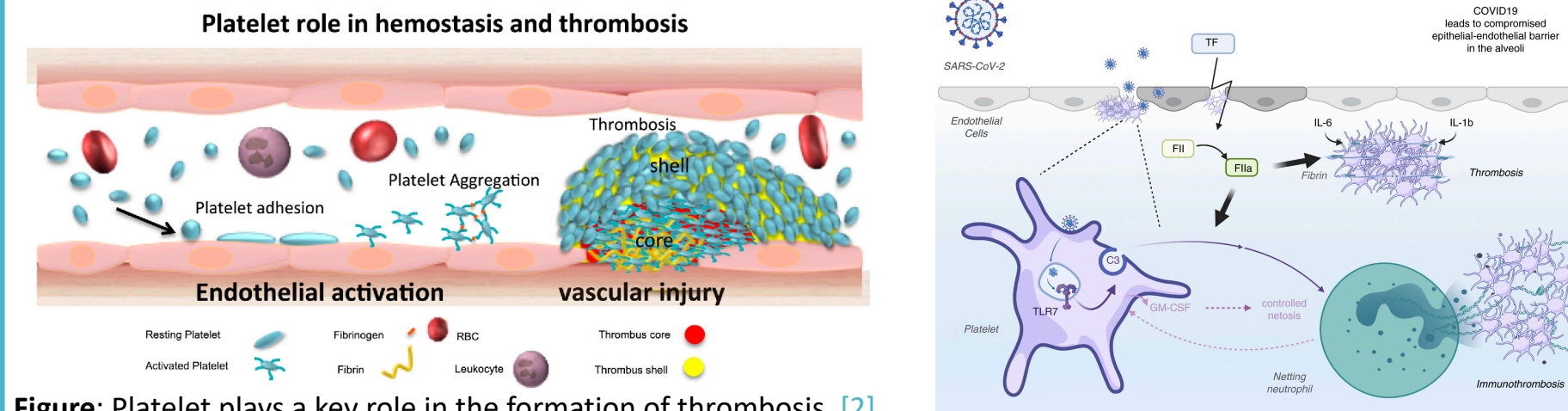


Figure: Platelet plays a key role in the formation of thrombosis. [2]

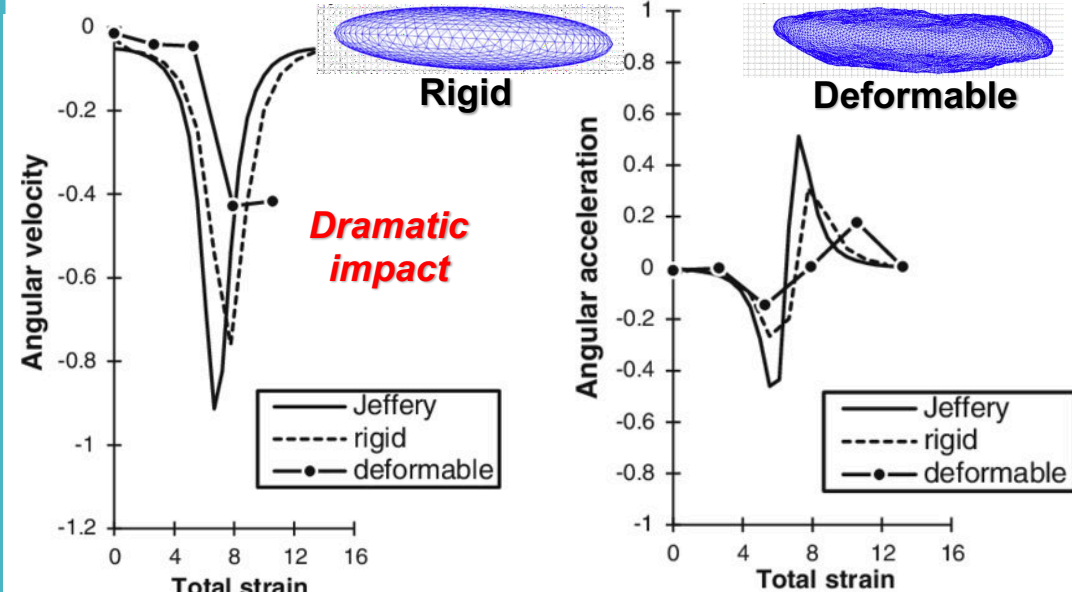


Figure: Comparisons of simulation results and Jeffery orbits. [4]

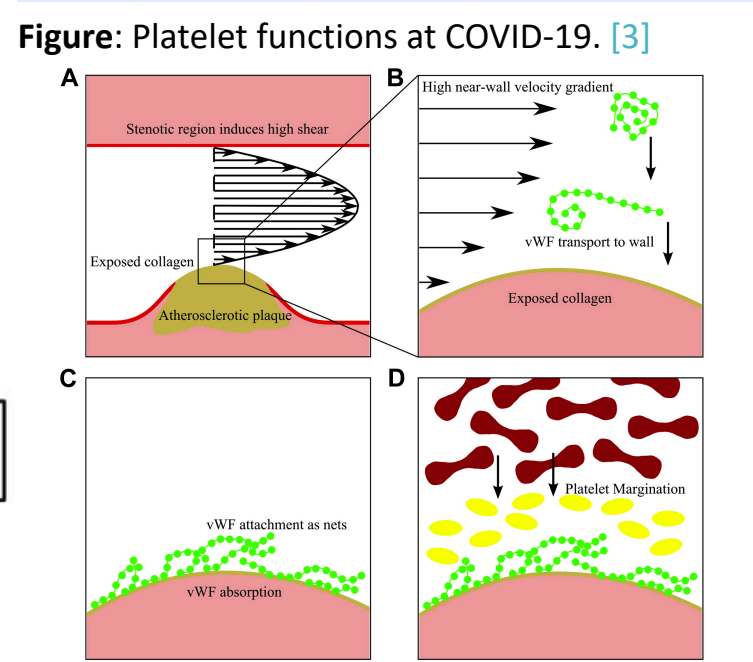


Figure: High shear thrombosis and stenosis. [5]

### Motivation:

- Generalizing the 100-year-old Jeffery orbits equation to describe the cell dynamics in biofluids with atomic resolution.
- Introducing the details of dynamic fluid-structure interaction (FSI) in modeling.
- Learning through one of fastest supercomputers for the basic dynamics of cell motion.

## HPC for Ground Truth

**Validation:** We model the motion of platelets using **multiscale modeling (MSM)**, which considers rotation of deformable platelets in viscous blood flows at the nano-to-microscales.

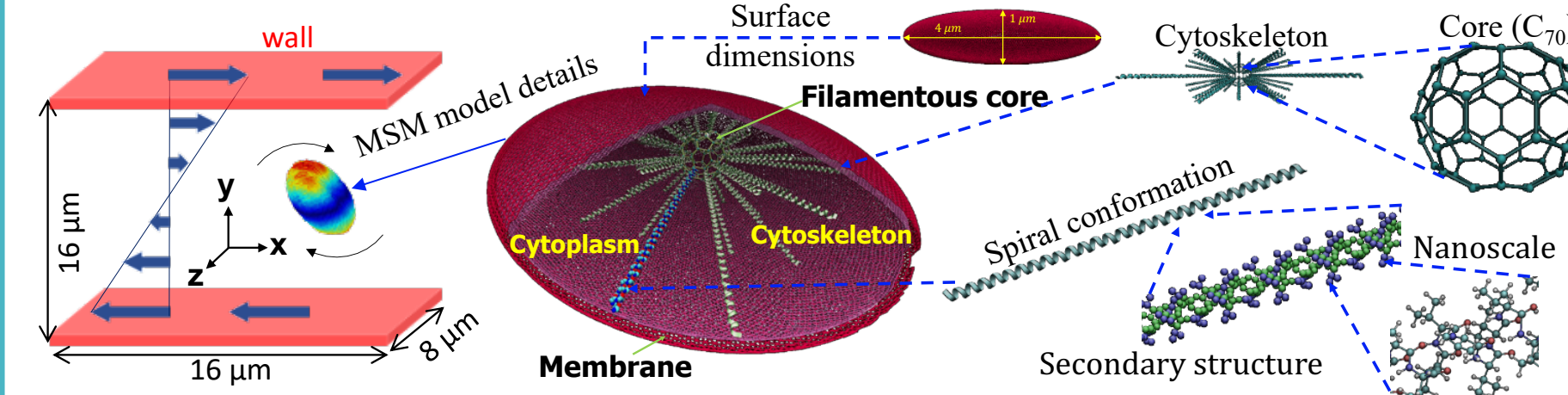


Figure: The system uses a total of 1,265,719 atoms: 1,091,360 atoms in flow and 140,303 atoms in platelet. In platelet, we use 40,446 atoms for cytoskeleton, 32,853 for cytoplasm and 67,004 for membrane.

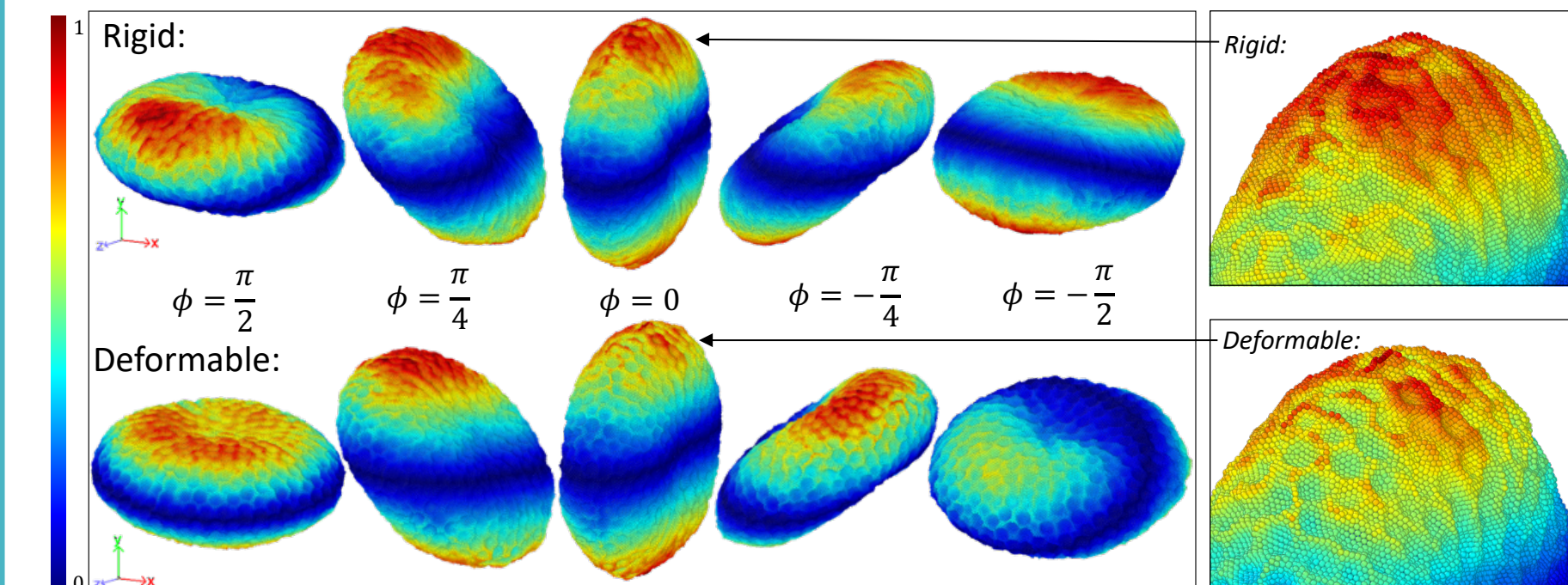


Figure: Velocity distribution for different positions of the rotation process, for rigid and deformable platelet body setups (left side). Zoom in to show the velocity distributions on membrane (right side).

## Online Learning for Equation of Motion

A generalized Jeffery orbits equation (G-JOE) of motion

$$\dot{\phi}(\dot{\gamma}t) = \frac{1}{2}(\lambda_0 + \lambda_1 \sin 2\phi)(\Lambda \cos 2\phi - c_0)$$

**Output variable:** Rotation angular velocity, Prediction of cell dynamics.  
**Input variable:** Rotation angle, Represent the cell motion.  
**Global variable:** Dimensionless time,  $\dot{\gamma}$ : shear rate of flow.  
**Learnable parameter:** Deviation from oblate (Initial value: 1), Deforming capability (Initial value: 0), Fluid-structure interaction (Initial value: -1).  
**Constant value:** From original Jeffery orbits ( $\frac{e^2-1}{e^2+1}$ ),  $e$ : initial aspect ratio.

Figure: The detailed parameter explanations of generalized Jeffery orbits equation

## A novel biomechanics-informed online learning framework

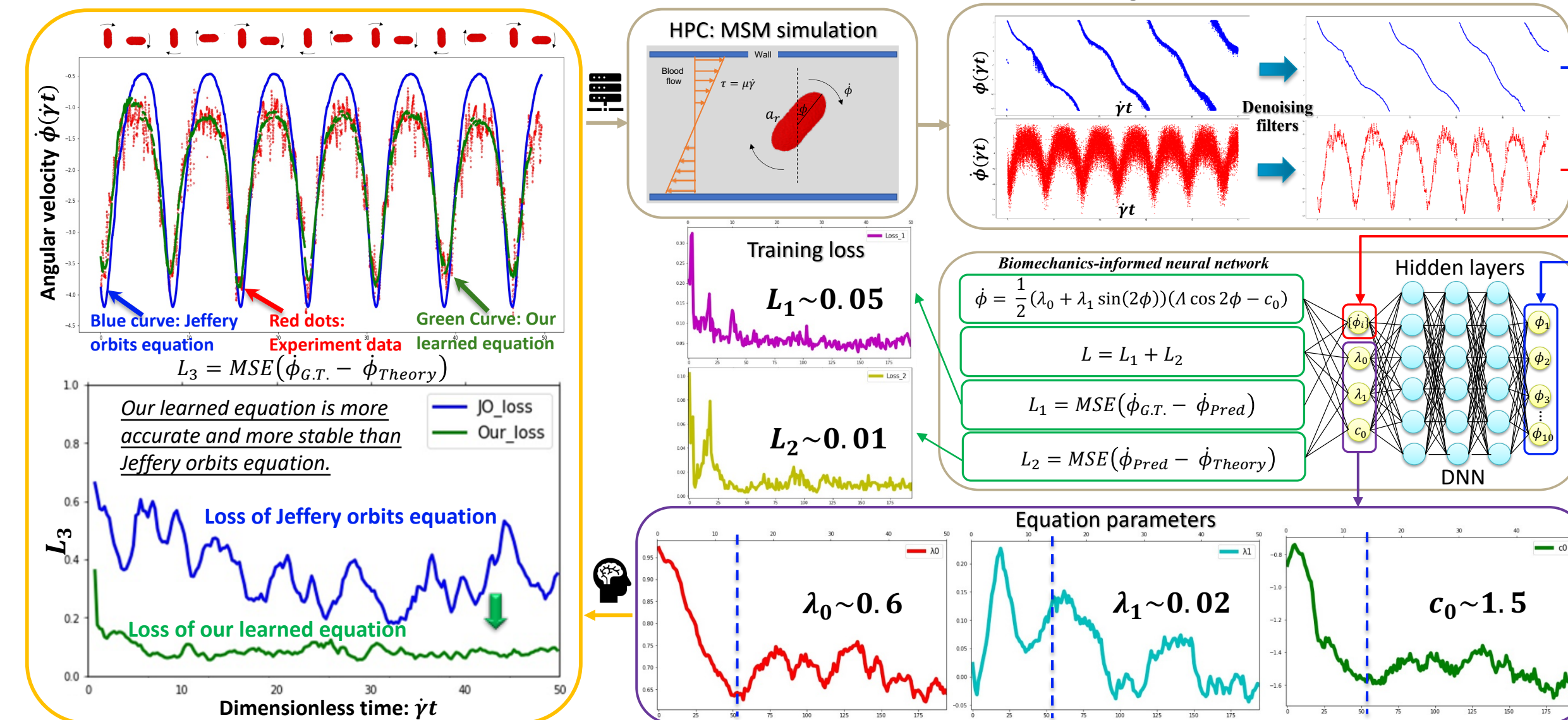


Figure: The BIOL provides a novel methodology framework for deriving equation parameters and consummate our modeling of dynamic system.

## Online Learning for Parameters

**Application:** We provide a fast and accurate way to determine FSI parameters in modeling, simplifying the dynamic systems and reducing the computation load.

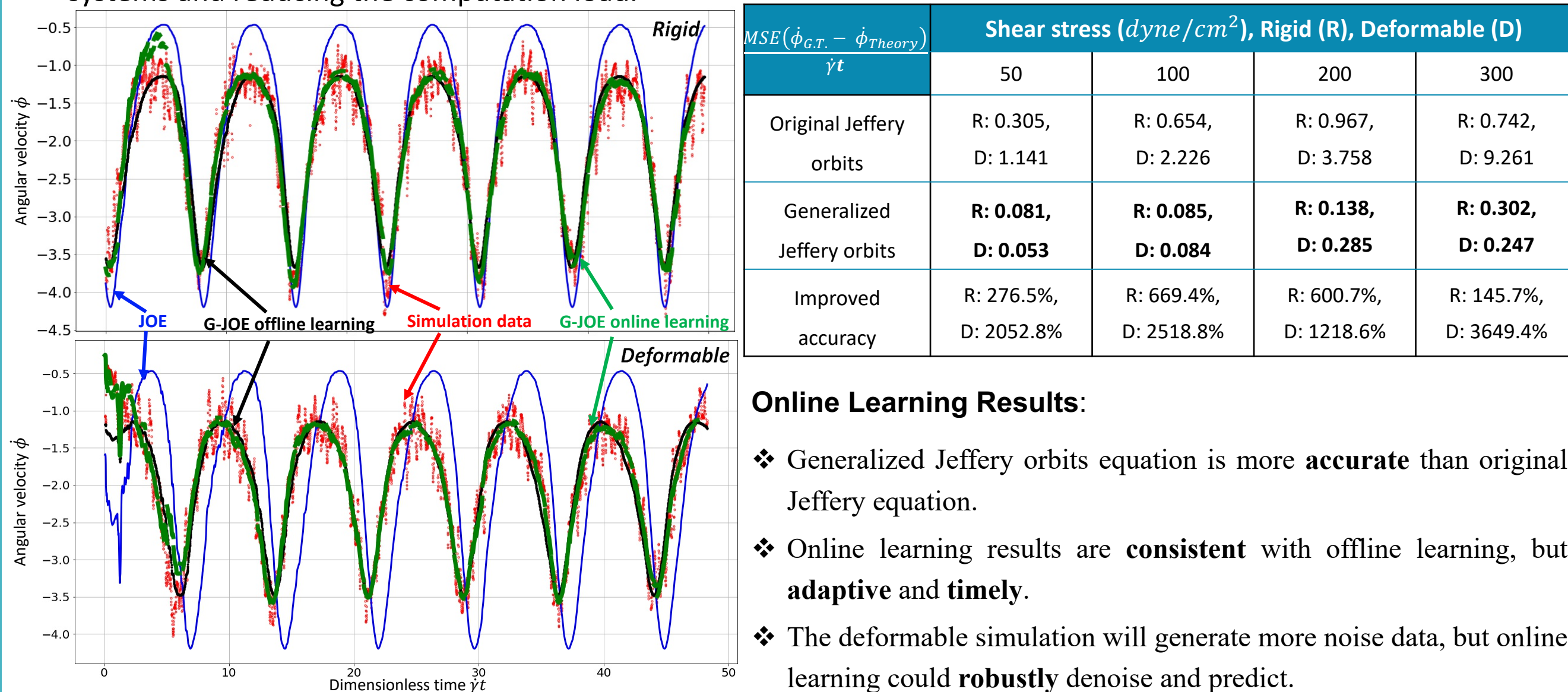


Figure: Angular velocity prediction comparisons under 50 dyne/cm<sup>2</sup>.

## Conclusions & Future Work

### Conclusions:

- The values of equation parameters are derived **consistently** for different flow conditions.
- Online learning could **adaptively** learn simulations even begin with numerical artifacts.
- MSM + BIOL could **save 90% of simulation time** without losing significant accuracy.

### Future work: Intelligent Supercomputing

- More than HPC:** we analyze our BIOL workflow and develop the AI + HPC framework.
- Future computing:** we work with IBM for the design of future HPC architecture.

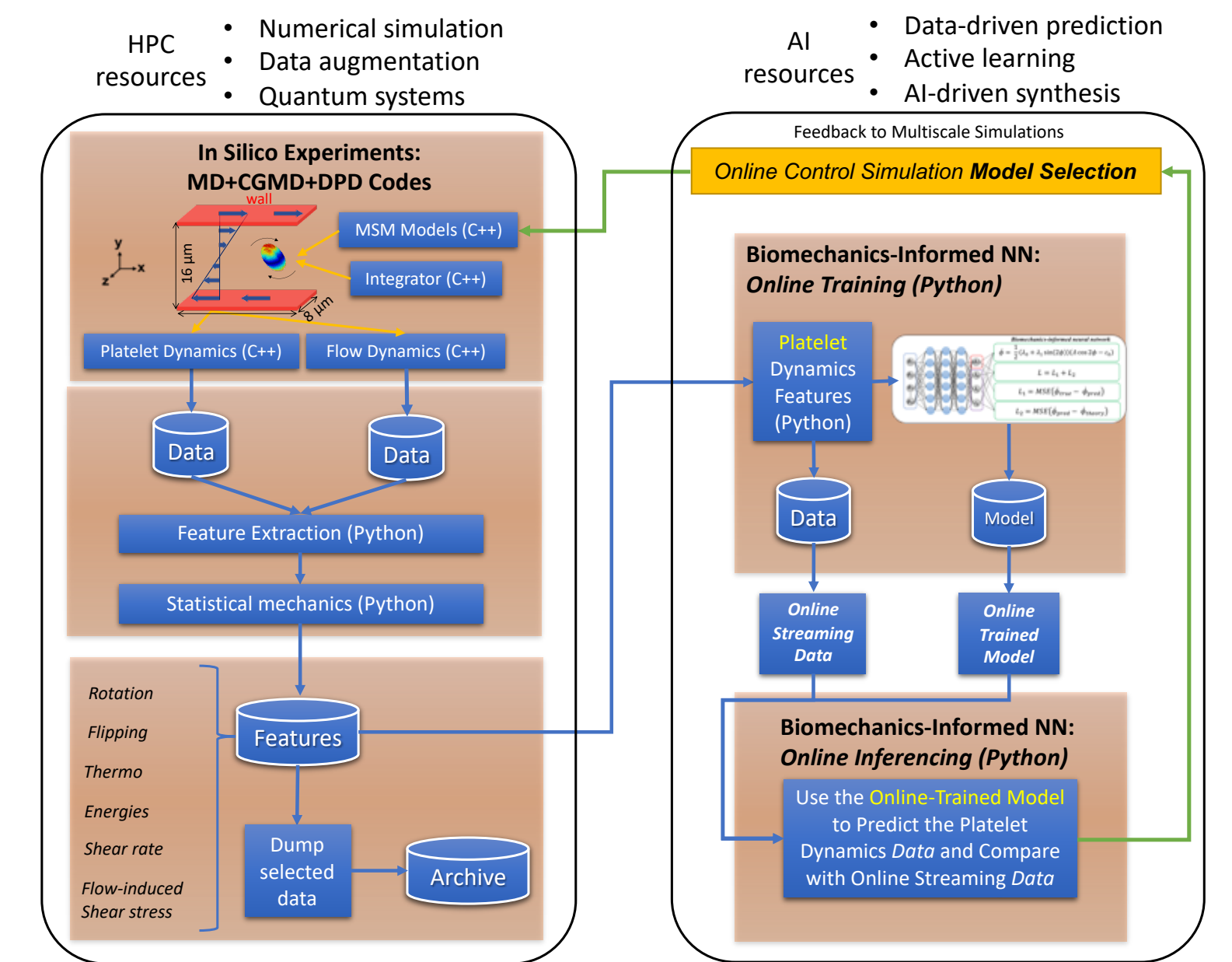


Figure: Proposed future computing architecture: accelerated discovery of knowledgebase

## The IBM Supercomputer AiMOS

Processor: IBM POWER9 20C 3.45GHz	GPUs: 1512 NVIDIA Volta GV100 (6/node)
Nodes: 252	Power Consumption: 512.08 kW
Cores: 130,000	Interconnect: Dual-rail Mellanox EDR Infiniband
Memory: 128,000 GB	Linpack Performance (Rmax): 8,339 TFlop/s
Nmax: 3,809,280	Theoretical Peak (Rpeak): 11,032 TFlop/s

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